

Algebraic Characterizations of Classes of Regular Languages in DynFO

Corentin Barloy, Felix Tschirbs, Nils Vortmeier, Thomas Zeume



Incremental maintenance and DynFO

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→ We refine this with **algebra**!

The algebraic theory

finite automaton \approx finite monoid (M, \cdot)

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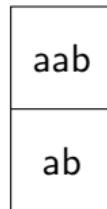
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Previous proof of $\text{Reg} \subseteq \text{DynFO}$: Maintain the evaluation of infixes in a monoid.

The regular languages of $UDyn\Sigma_2$

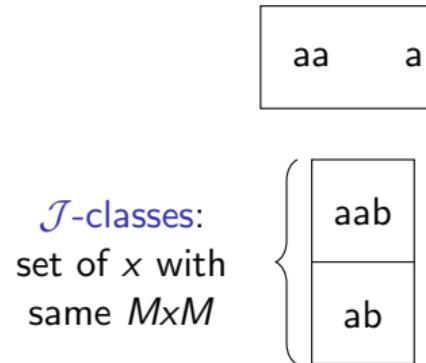
Ideal structure

A **division-based** representation of the syntactic monoid of $(aa)^*b(a + b)^*$:



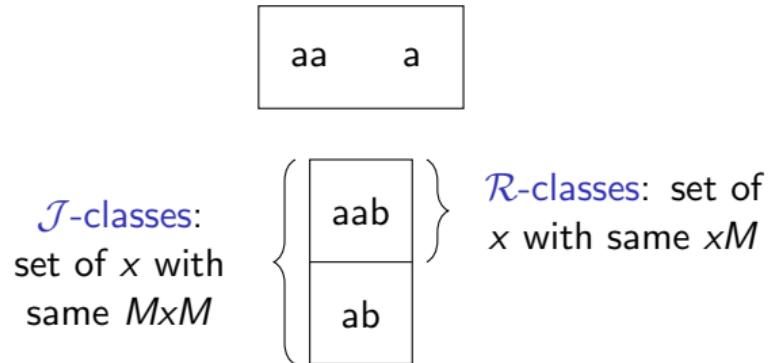
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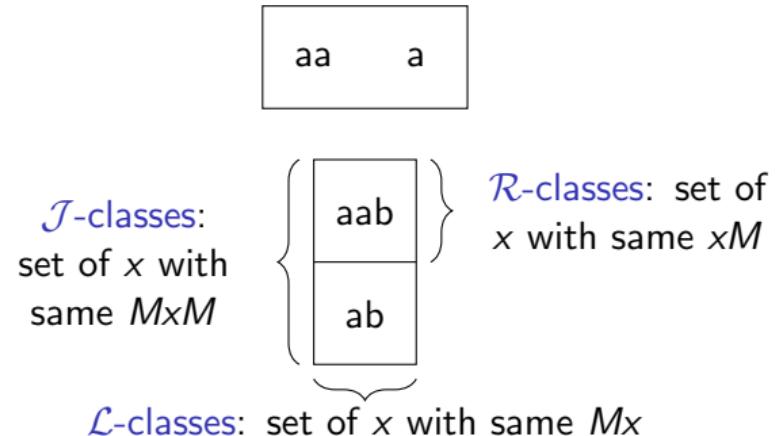
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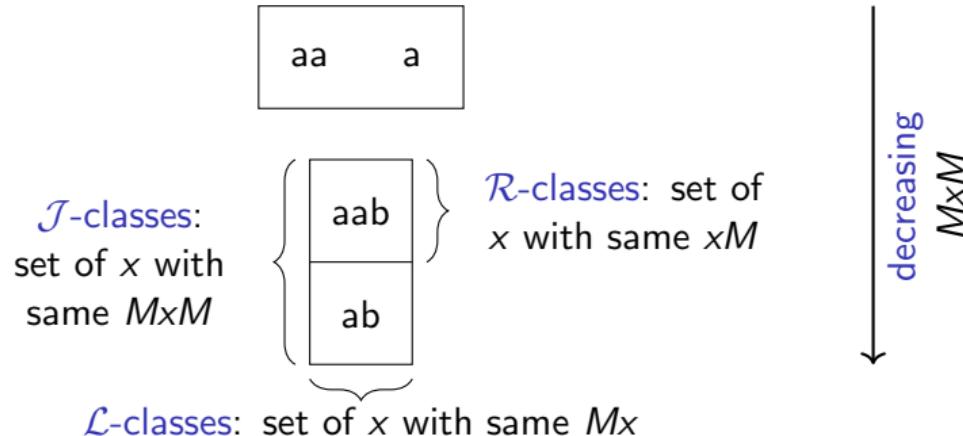
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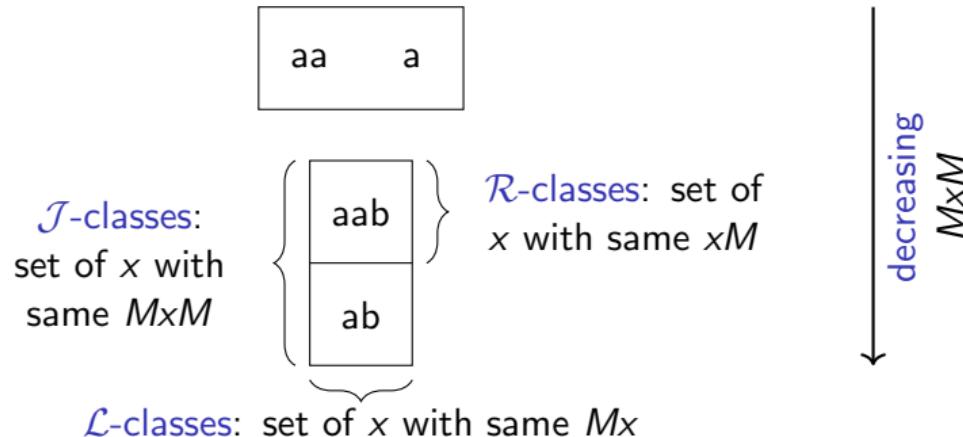
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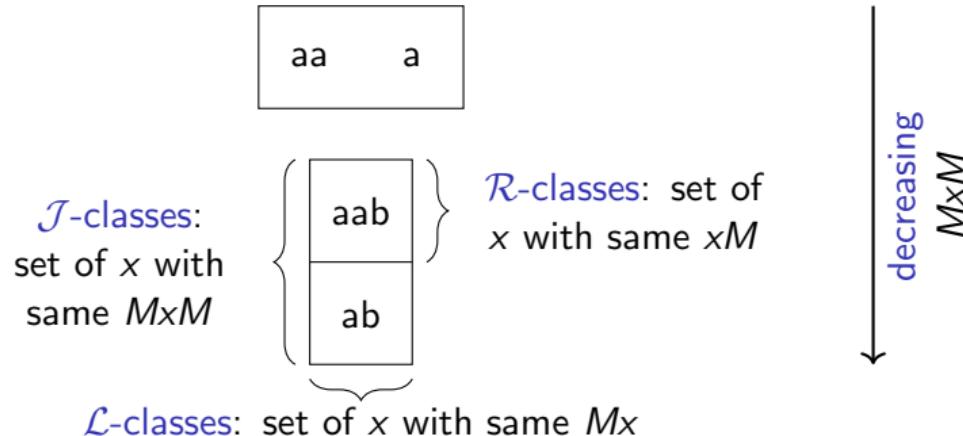
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$$\begin{array}{ccccccccccccccccc} w_1 & \dots & w_{l_1} & w_{l_1+1} & \dots & w_{l_2} & w_{l_2+1} & \dots & w_n \\ \underbrace{w_1 \quad \mathcal{J} \quad x_1 \quad <_{\mathcal{J}} \quad x_1 w_{l_1+1}}_{\mathcal{J}} \\ \underbrace{x_2 \quad <_{\mathcal{J}} \quad x_2 w_{l_2+1}}_{\mathcal{J}} \\ \vdots \\ \underbrace{x_m}_{\mathcal{J}} \end{array}$$

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All [regular languages](#) are in $\text{UDyn}\Sigma_2$.

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We can check if $w[i,j]$ evaluates to x in Σ_2 :

$\exists i = l_1 < \dots < l_m = j$,

→ $\forall l_k \leq j < l_{k+1}$, there is **no jump** in \mathcal{J} -class at j (thanks to L)

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Updates of $R_{J,x}$ at i : there is an index j such that $w[i,j]$ evaluates to x and $w[i,j+1]$ is $> J$.

The regular languages of UDynProp

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\rightarrow **G** is the class of languages whose syntactic monoid is a group

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[Schwentick, Zeume 2015]

The regular languages of $UDyn\Sigma_1^+$

Positive varieties

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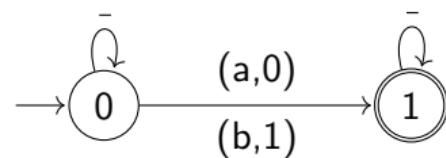
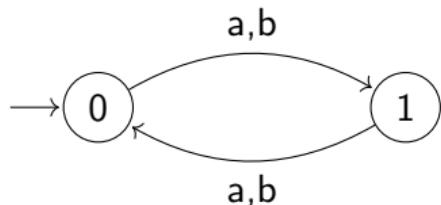
→ Membership of a language in a positive variety only depends on its syntactic ordered monoid

Wreath products

Sequential composition of automata \mathcal{A}_1 and \mathcal{A}_2 : on input w , label w by the states it reaches in \mathcal{A}_1 and feed it to \mathcal{A}_2 .

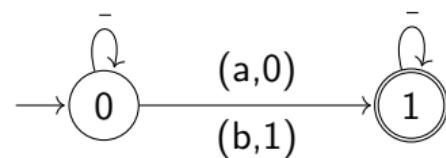
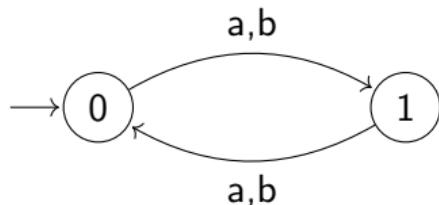
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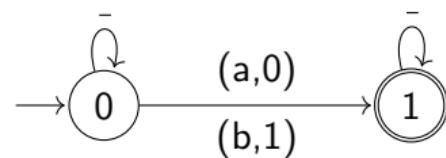
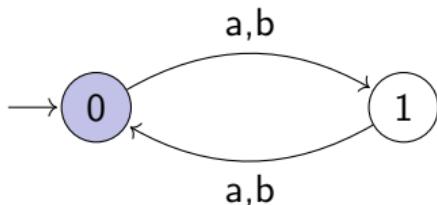
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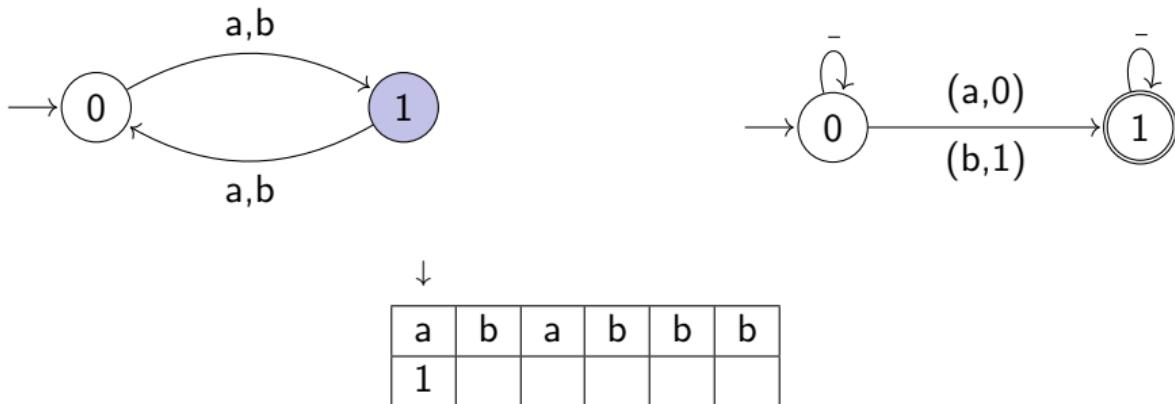
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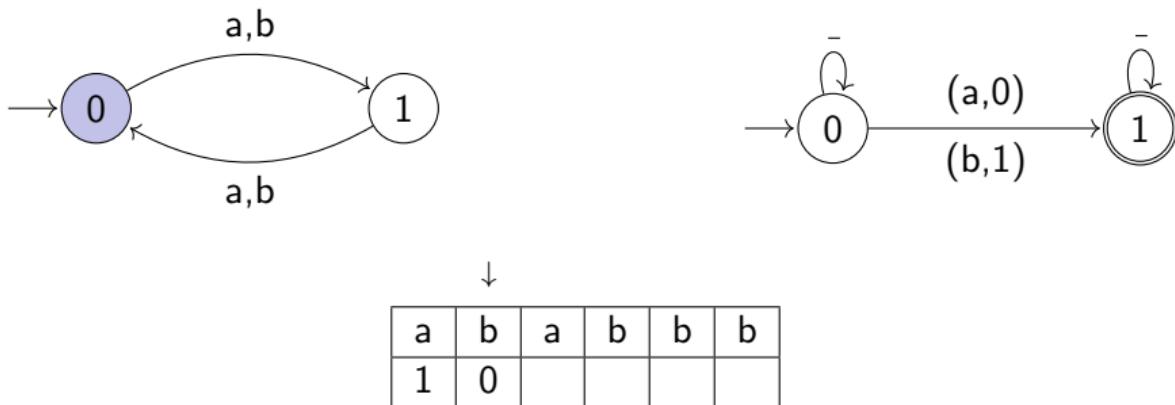
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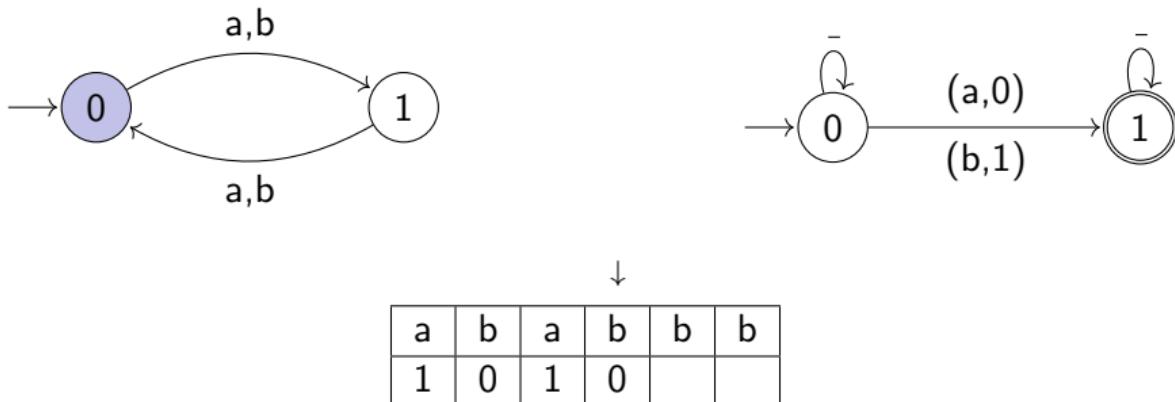


↓

a	b	a	b	b	b
1	0	1			

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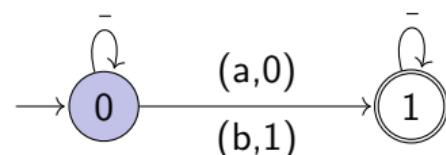
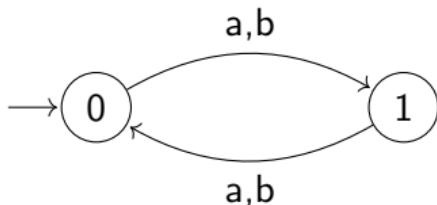


↓

a	b	a	b	b	b
1	0	1	0	1	0

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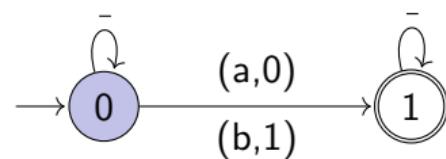
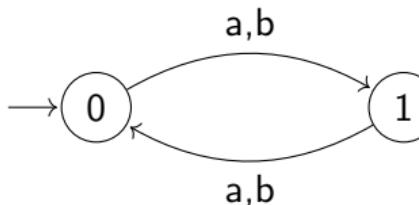
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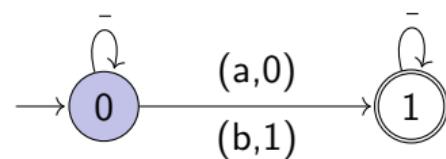
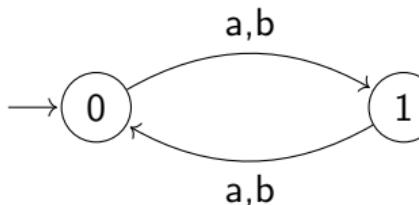


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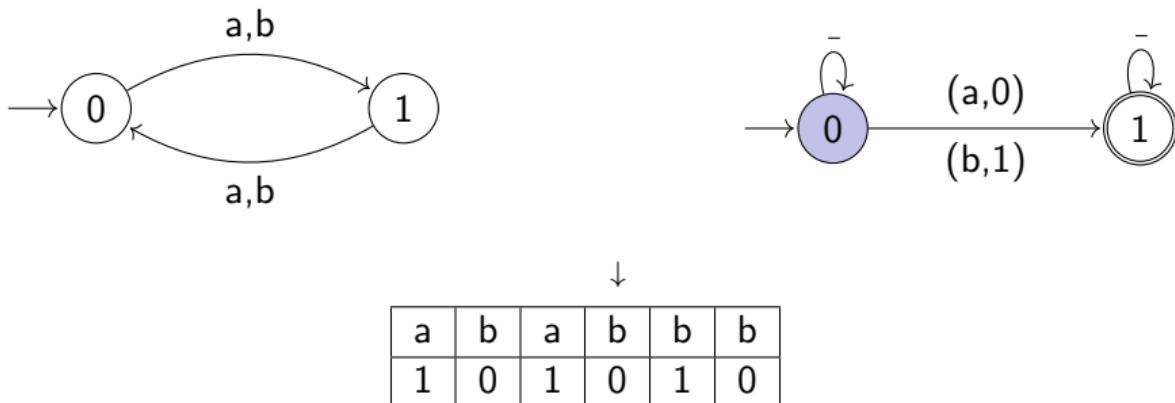
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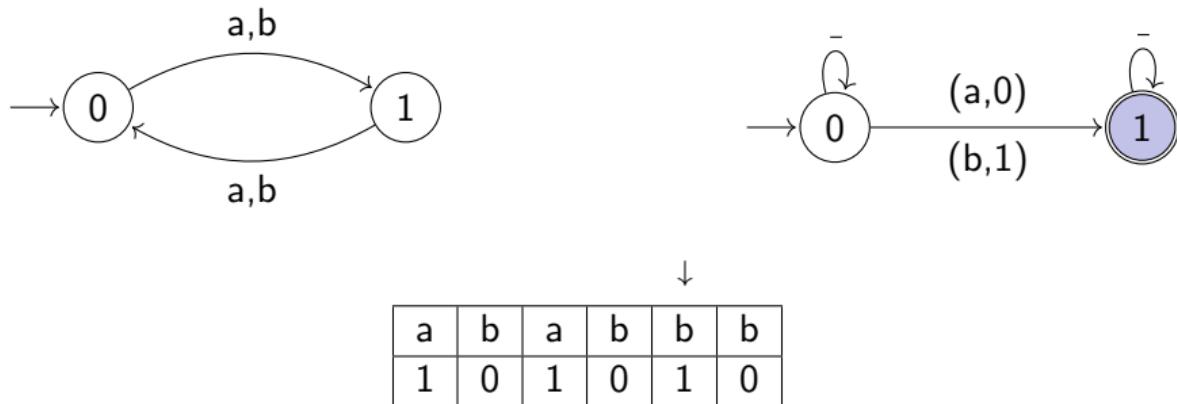
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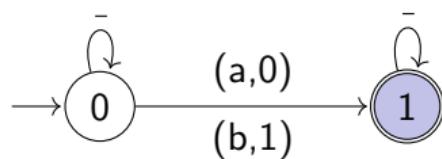
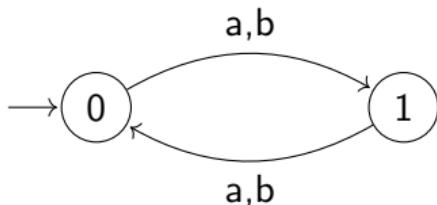
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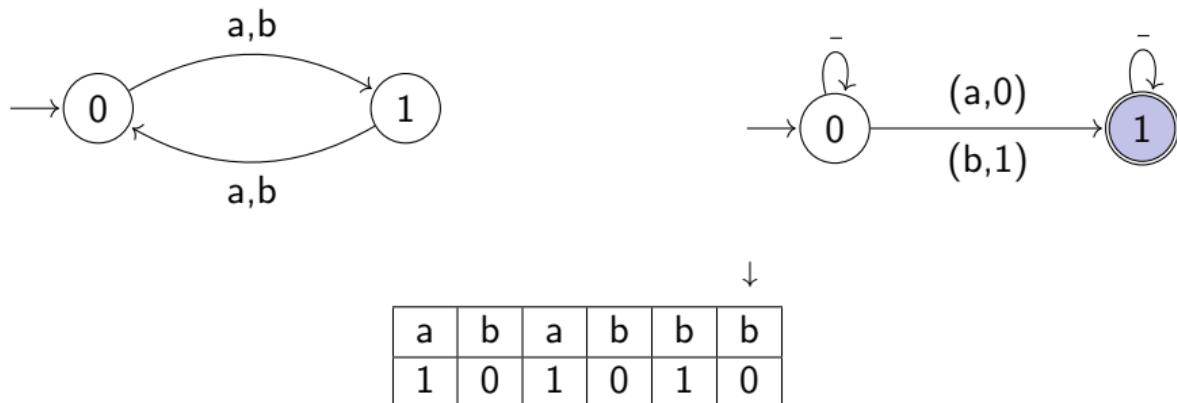


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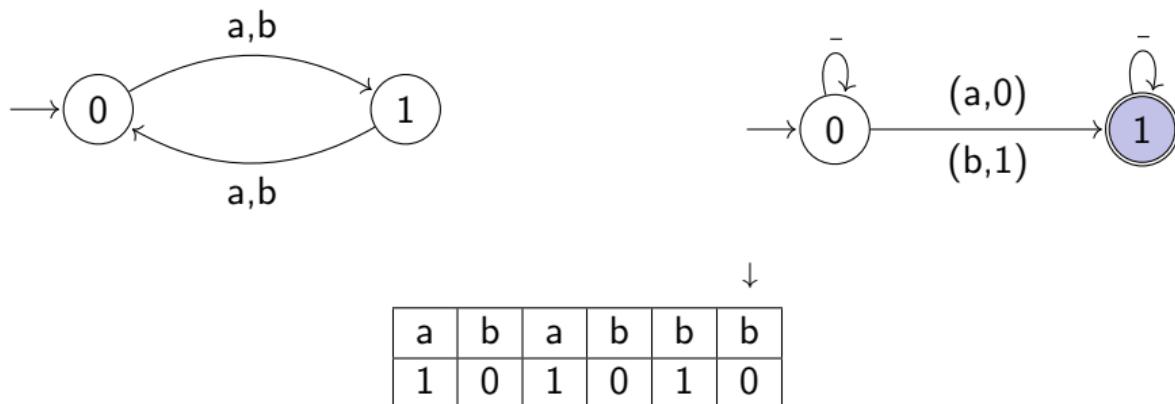
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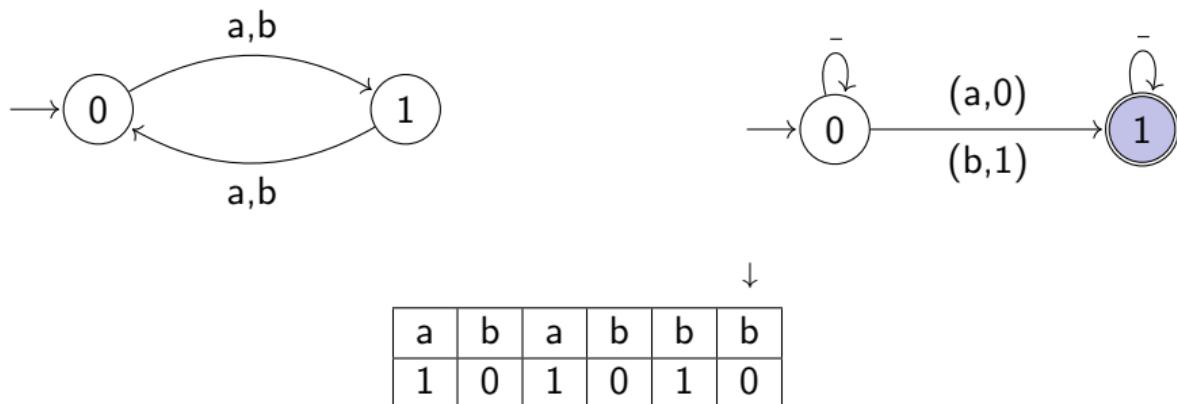


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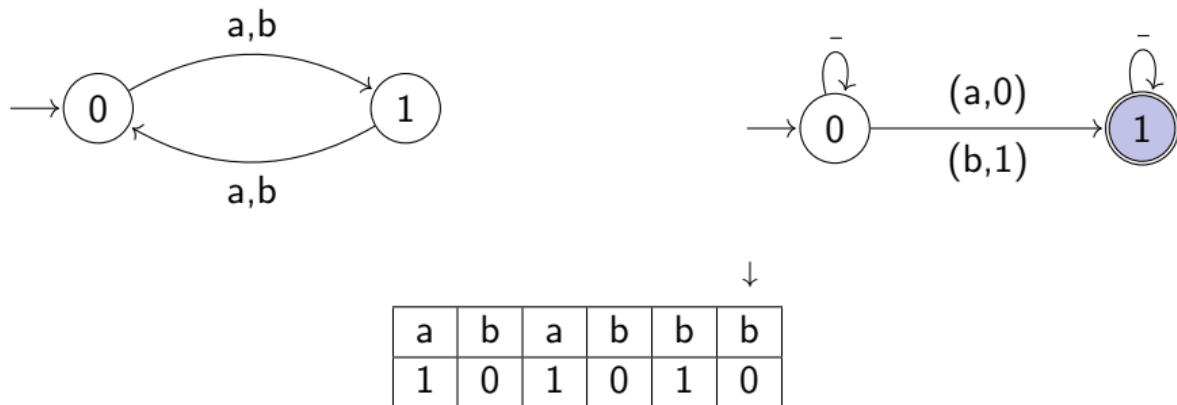


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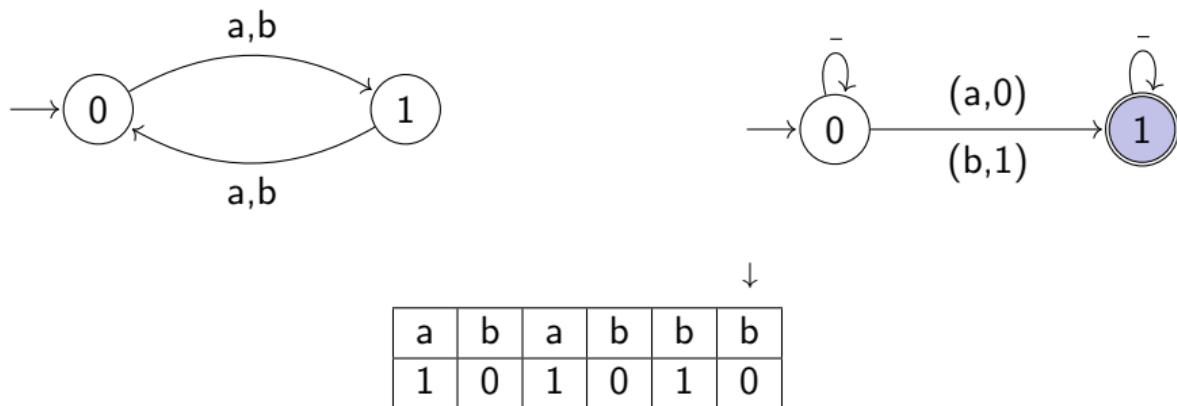
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Recap:

Dynamic class	UDynProp	$\text{UDyn}\Sigma_1^+$	$\text{UDyn}\Sigma_2$
Regular languages	\mathbf{G}	$\mathbf{J}^+ * \mathbf{G}$	Reg